





ASWSC Phase 3

Migration of the Automated Safety Warning System Controller to the Caltrans Advanced Transportation Controller Platform

Need and Background Part 1 of 6

Jeremiah Pearce P.E., Caltrans District 2

Jeff Worthington, Caltrans District 2

Doug Galarus, Montana Tech













The Automated Safety Warning System Controller (ASWSC) was developed through a multi-phased research and development effort by Caltrans and the Western States Rural Transportation Consortium (WSRTC). The ASWSC interfaces with roadside sensors and signs to actuate safety warning messages such as icy curve and high wind warnings. For instance, wind warning messages may be actuated on a changeable message sign (CMS) when wind speed, as read from an RWIS sensor, exceeds a given threshold. The ASWSC allows for automated data collection and application of best practice algorithms to analyze sensor data and to actuate related warning messages and signals in real time. The hardware and software system was pilot tested by multiple users and over multiple years in the field in preparation for wider deployment. While the system was developed on an industrial hardware platform and standard Linux, and performed very well in the field, it became desirable to deploy the system using Caltrans' Linux-based Advanced Transportation Controller (ATC), which is now available for purchase from multiple vendors and standardized for Caltrans. This presentation will cover project history, detailed architecture and current status.











Original Problem Statement

In order to provide better safety warning information to motorists, how can roadside condition sensor data be automatically analyzed, and real-time road condition information be displayed to the traveling public?

[Caltrans Research Problem Statement - 2005]











Original Problem Statement

Automated warning systems are not a new concept within the transportation community... To date, all of these systems are unique implementations that use one-of-a-kind software for control... A standardized automated warning system controller, which controls standardized field elements in a system environment, has not been developed to date.

[Caltrans Research Problem Statement - 2005]













- **1.** Background Need and Purpose Jeremiah Pearce
- 2. Development Phases 1 and 2 Doug Galarus
- 3. Deployment and Testing Phases 1 and 2 Jeremiah Pearce
- 4. Development Phase 3 Doug Galarus
- 5. Deployment and Testing Phase 3 Jeff Worthington
- 6. Concluding Remarks and What's Next Jeff, Doug, and Jeremiah







LOOKING E/B AT PM 50.5 LOCATION OF RWIS AND PAVEMENT SENSORS

Part 1 of 6

LOOKING E/B AT PM 50.5 LOCATION OF RWIS AND The Problem

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Ice

Weather Induced Localized Incidents

LOOKING E/B AT PM 50.5 LOCATION OF RWIS AND The Problem



Weather Induced Localized Incidents
Ice and Snow

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Spring Garden RWIS and CCTV

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Part 1 of 6

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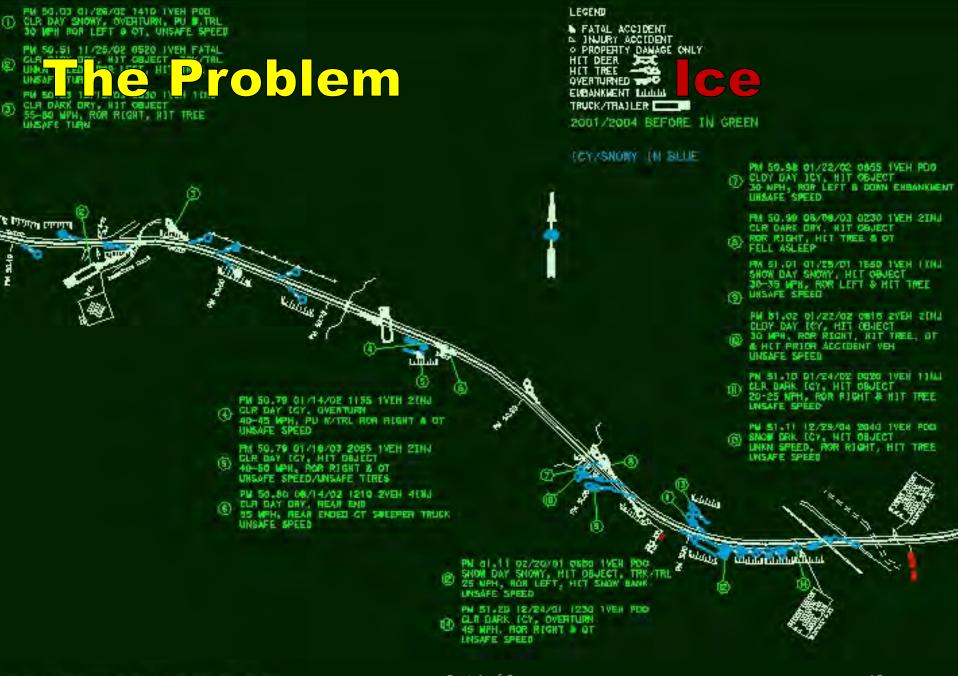


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Part 1 of 6

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ING GARDEN BEFORE & AFTER ACCIDENT PLOT 70 PM 50.0/51.3



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Part 1 of 6

The Problem

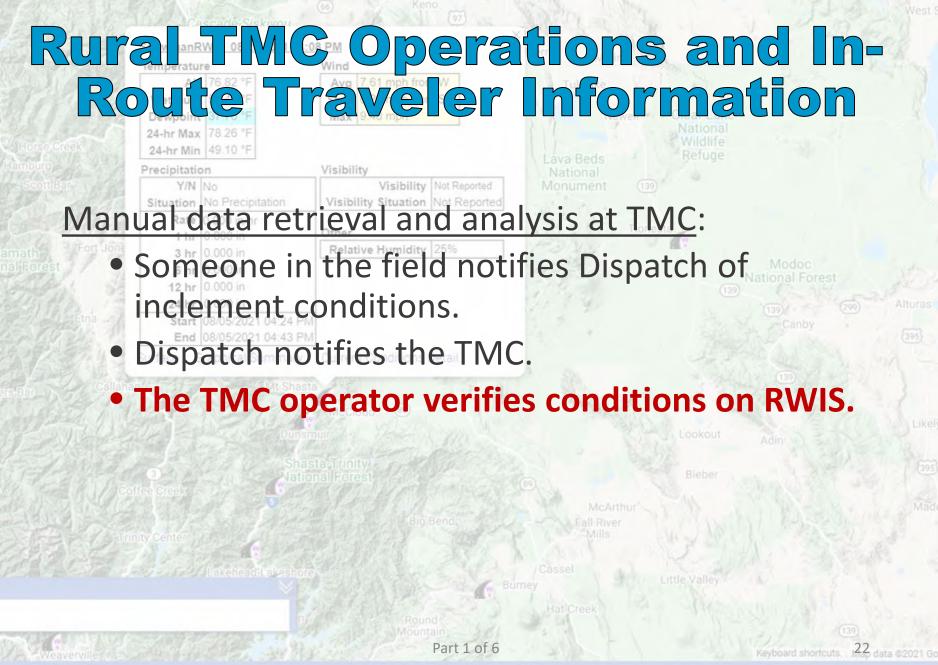


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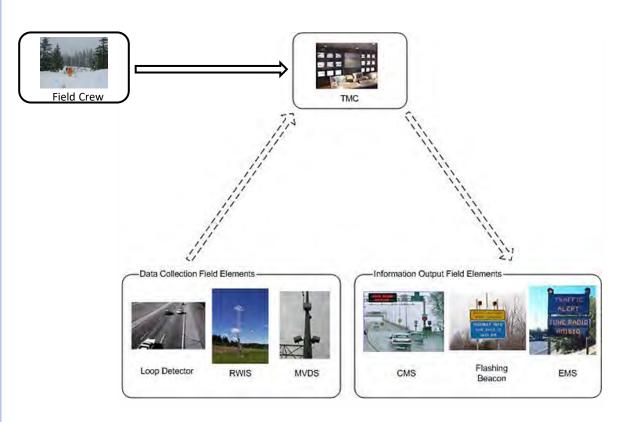
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Manual data retrieval and analysis at TMC:

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- The TMC operator verifies conditions on RWIS.
- The TMC operator manually sets the warning (CMS, EMS, Flashing beacon).

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TMC Monitoring and Warning Message Activation

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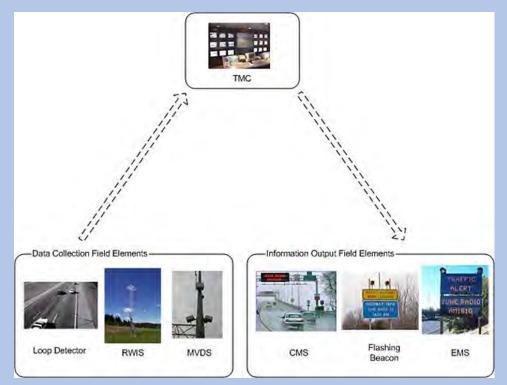
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Part 1 of 6

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- Off hours issues TMC not manned 24/7
- Process often breaks down at the warning removal step

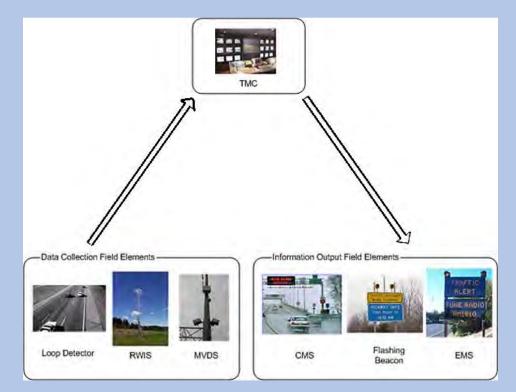
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- The application sets warning messages and activates field elements.
- The application monitors conditions and removes the warning when conditions improve.
- Requires a dedicated and reliable, highbandwidth connection between the field elements and the TMC.



Central System Automated Warning System

Part 1 of 6

Problems with the Central Systems Approach:

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• A dedicated and reliable high-bandwidth connection between the field elements and the TMC is often unavailable in remote rural locations.







Can we automate this process in the field?

We can and we have!



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History at Fredonyer – It's Complicated!



- History at Fredonyer It's Complicated!
 - See Ken Beals' detailed analysis, "A Tale of Two RWIS".

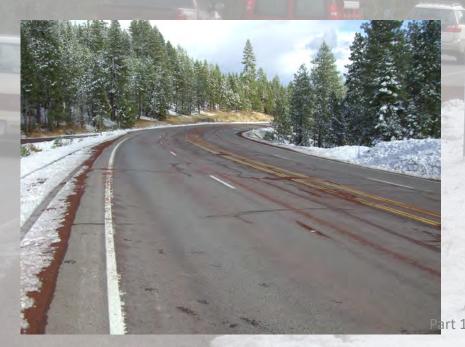
http://www.westernstatesforum.org/PastForums/2008/ Default.html



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- Similar site conditions to Spring Garden.



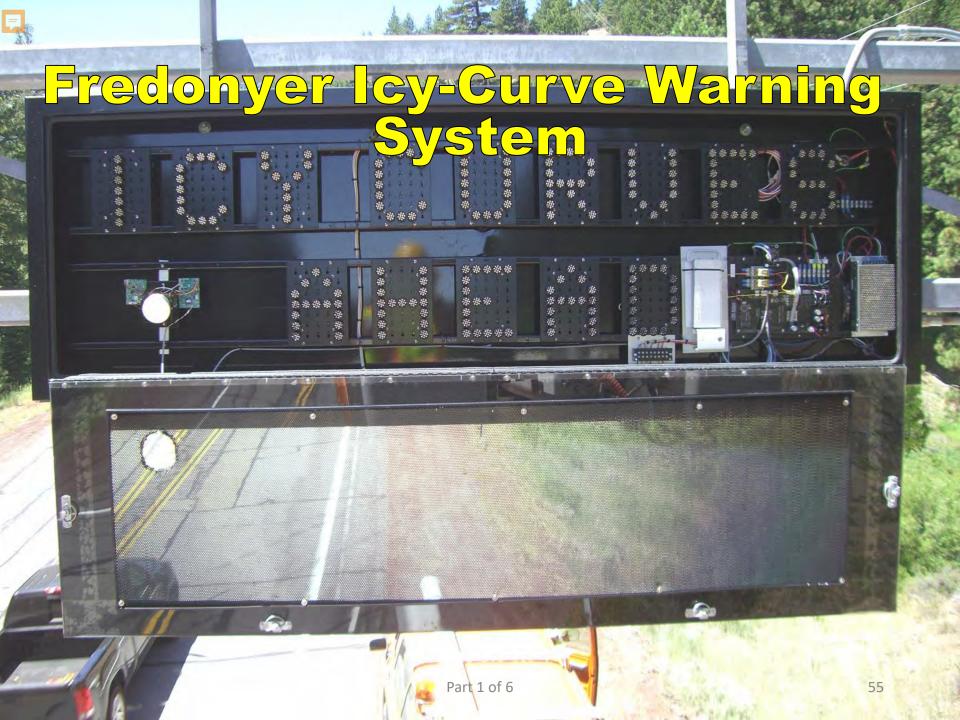


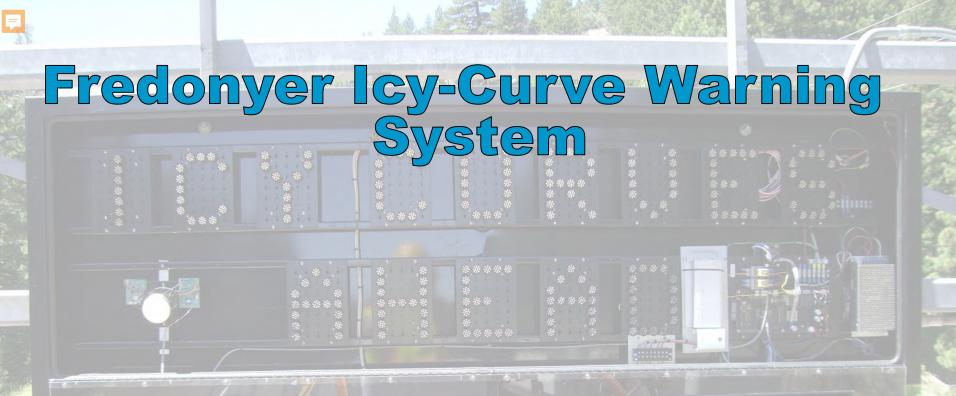
• 2011 study indicates an 18% reduction in crashes.

 <u>Veneziano (2011) - "Evaluation of the Fredonyer</u> Pass Icy Curve Warning System"

• So why not duplicate the architectural model of Fredonyer at Spring Garden?







• Fredonyer was built for a single type of warning system



The System architecture and components are unique to the installation

Fredonyer Icy-Curve Warning System Problems with the architecture at Fredonyer:

Part 1 of 6

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- Interoperability and integrating obsolete equipment replacements.

ICY CURVES AHEAD

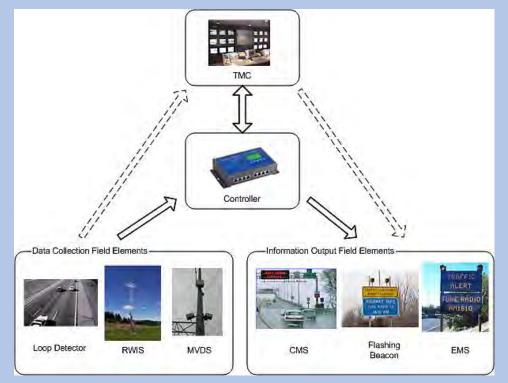
What we need is a field controller that:

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- Can be accessed remotely when needed, but functions if communication to the TMC is interrupted.
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- Is a standard form factor familiar to Caltrans Electrical Maintenance crews.



ASWSC System Architecture

• A research project was initiated with the Western Transportation Institute (WTI) at Montana State University.

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- The Spring Garden site, constructed in 2005 would function as the test bed for the ASWSC.

The Automated Safety Warning Spring Systems Controller (ASWSC) Test Bed

Spring Garden RWIS and CCTV

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Spring Garden CMS East •

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• References

- "A Tale of Two RWIS", Ken Beals (2008). http://www.westernstatesforum.org/PastForums/2008/Default.html
- "Evaluation of the Fredonyer Pass Icy Curve Warning System", David Veneziano (2011).
- "Automated Safety Warning System Controller", Ed Lamkin and Ian Turnbull (2010).

• Photos Courtesy Of,

- Ian Turnbull
- Doug Galarus
- Dan Richter
- Ken Beals
- Jeff Worthington

- District 2 ITS Engineering and Support
- District 2 Traffic Safety
- Google Maps
- Google Street View
- Part 3 of 6 Google Images